# Modified Regression Type Estimators in the Presence of Non-Response in Two Phase sampling 

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#### Abstract

: It is a common experience in sample survey that data cannot always be collected for all units selected in the sample at the first attempt and even after some call-backs. An estimate obtained from such incomplete data may be misleading because of the non-response in the data. In addition, the population mean of the auxiliary variable from the previous census may not be available. In this paper, Modified regression type estimators proposed by Tum et al. (2014) in single phase sampling, assuming complete response, have been proposed to estimate the population mean of the study variable in the presence of non-response under two phase sampling scheme. The expression of mean squared errors (MSE) based on the proposed estimators have been derived under two phase sampling to the first degree of approximation. A comparison of the proposed estimators with the usual unbiased estimator and existing estimators under two phase sampling scheme have been carried out. The proposed Modified regression type estimators have been found to be the most efficient compared to the existing estimators and they are recommended for use in practice.


Keywords: Modified regression type estimators, Study variable, Auxiliary variables, Mean Square Error, Non-response.

## 1. Introduction

It is a common experience in sample survey that data cannot always be collected for all units selected in the sample. For example in a household survey, the families may not be found at home at the first attempt and some may refuse to cooperate with the interviewer even if contacted. In general, during surveys, it is observed that information in most cases is not obtained at the first attempt even after some call-backs. The failure to measure or get information from some of the units in the selected sample is referred to as non-response. An estimate obtained from such incomplete data may be misleading because of the non-response. There are various practical reasons for this incomplete information due to non-response like unwillingness of the respondent to answer some particular questions, accidental loss of information caused by unknown factors and failure on the part of investigator to collect the correct information, etc. The usual approach to face the non-response is
to re-contact the non-respondents and obtain the information. Hansen and Hurwitz (1946) were the first authors to contract the problem of nonresponse while conducting mail surveys. They suggested a technique, known as 'sub-sampling of non-respondents', to deal with the problem of nonresponse and its adjustments. In fact they developed an unbiased estimator for population mean in the presence of non-response by dividing the population into two groups, viz. response group and non-response group. To avoid bias due to non-response, they suggested taking a subsample of the non-responding units. Neyman (1938)
developed the concept of double phase sampling in sample survey. This sampling scheme is used to obtain the information about auxiliary variable cheaply from a larger sample at first phase and relatively small sample at the second stage. Khare and Srivastava $(1993,1995)$ proposed ratio, product and regression estimators when population
mean of auxiliary variable X is known and nonresponse occur only in the study variable in two phase sampling. Singh et al. (2010) proposed Exponential ratio and Exponential product estimators when population mean of auxiliary variable X is known and non-response occur only in the study variable in two phase sampling. Kumar and Bhougal (2011) proposed Exponential ratio-product estimator when population mean of auxiliary variable X is known and non-response occur only in the study variable in two phase sampling. Khare and Srivastava $(1993,1995)$ also proposed ratio, product and regression estimators when population mean of auxiliary variable X is unknown and non-response occurs in both the study variable and auxiliary variable in two phase sampling. Singh et al. (2010) also proposed Exponential ratio and Exponential product estimators when population mean of auxiliary variable X is unknown and non-response occur occurs in both the study variable and auxiliary variable in two phase sampling. Kumar and Bhougal (2011) also proposed Exponential ratioproduct estimator when population mean of auxiliary variable X is unknown and non-response occurs in both the study variable and auxiliary variables in two phase sampling. Tum et al. (2014) proposed a regression type estimator that combined regression estimator and ratio - product type exponential estimator to form a new modified regression estimator. This study will focus on Tum et al. (2014) in presence of non-response in the study variable only and in both the study variable and auxiliary variables and develop their mean squared errors by incorporate Arora and Lal (1989) approach in writing down the mean squared error.

## 2. Notation

Consider a finite population of size $N$ and a random sample of size $n$ drawn without replacement. In surveys on human populations, frequently $n_{1}$ units respond on the items under examination in the first attempt while remaining $n_{2}\left(=n-n_{1}\right)$ units do not provide any response. When non-response occurs in the initial attempt, Hansen and Hurwitz (1946) proposed a double sampling scheme for estimating population mean comprising the following steps:
i) a simple random sample of size $n$ is selected and the questionnaire is mailed to the sampled units;
ii) a sub sample of size $r=\left(n_{2} / k\right),(k \geq 1)$ from the $n_{2}$ non-responding units in the initial attempt is contacted through personal interviews.
Consider a finite population of size $N$. We draw a sample of size $n$ from a population by using simple random sample without replacement (SRSWOR) sampling scheme. Let $y_{i}$ and $x_{i}$ be the observations on the study variable ( y ) and the auxiliary variable (x) respectively. Let $\bar{Y}=\frac{1}{N} \sum_{i=1}^{N} y_{i} \quad$ and $S_{y}^{2}=\frac{1}{N-1} \sum_{i=1}^{N}\left(y_{i}-\bar{Y}\right)^{2}$ denote the population mean and the population variance of the survey variable $y$. When information on $\bar{X}$ is unknown then double sampling or two phase sampling is suitable to estimate the population mean. In the first phase sample we select a sample of size $n^{\prime}$ by SRSWOR from a population to observe $x$. In the second phase, we select a sample of size $n$ from $n^{\prime}$ such that $n<n^{\prime}$ by SRSWOR also. Non-response occurs on second phase in which $n_{1}$ units respond and $n_{2}$ do not out of $n$ units. From $n_{2}$ non-respondents a sample of $r=\left(n_{2} / k\right),(k>1)$ units are selected, where $k$ is the inverse sampling rate at the second phase sample of size $n$. Let $\bar{Y}_{1}=\frac{1}{N_{1}} \sum_{i=1}^{N_{i}} y_{i}$ and $S_{y(1)}^{2}=\frac{1}{N_{1}-1} \sum_{i=1}^{N_{1}}\left(y_{i}-\bar{Y}_{1}\right)^{2}$ denote the mean and variance of the response group. Similarly, $\bar{Y}_{2}=\frac{1}{N_{2}} \sum_{i=1}^{N_{2}} y_{i}$ and $S_{y(2)}^{2}=\frac{1}{N_{2}-1} \sum_{i=1}^{N_{2}}\left(y_{i}-\bar{Y}_{2}\right)^{2}$ denote the mean and variance of the non-response group. The population mean can be written as $\bar{Y}=W_{1} \bar{Y}_{1}+W_{2} \bar{Y}_{2}$, where $W_{1}=\left(N_{1} / N\right)$ and $W_{2}=\left(N_{2} / N\right)$. Let $\bar{y}_{1}=\frac{1}{n_{1}} \sum_{i=1}^{n} y_{i}$ and $\bar{y}_{2}=\frac{1}{n_{2}} \sum_{i=1}^{m_{2}} y_{i}$ denote the means of the $n_{1}$ responding units and the $n_{2}$ non-responding units. Further, let $\bar{y}_{2 r}=\frac{1}{r} \sum_{i=1}^{r} y_{i}$ denote the mean of the $r$ $=n_{2} / k$ sub sampled units.
Thus, an unbiased estimator, due to Hansen and Hurwitz (1946) of the population mean $\bar{Y}$ of the study variable $y$ is given by,

$$
\begin{equation*}
\bar{y}^{*}=w_{1} \bar{y}_{1}+w_{2} \bar{y}_{2 r} \tag{1}
\end{equation*}
$$

Where $w_{1}=\left(n / n_{1}\right), \quad w_{2}=\left(n / n_{2}\right)$ are responding and non-responding proportions in the sample. The variance of $\bar{y}^{*}$ to terms of order $n^{-1}$ is given by,

$$
\begin{equation*}
V\left(\bar{y}^{*}\right)=\bar{Y}^{2}\left\{\theta C_{y}^{2}+\lambda C_{y(2)}^{2}\right\} \tag{2}
\end{equation*}
$$

where $\theta=\frac{N-n}{N n}, \lambda=\frac{W_{2}(k-1)}{n}$,
$C_{y}^{2}=\left(S_{y}^{2} / \bar{Y}^{2}\right)$ and $C_{y(2)}^{2}=\left(S_{y(2)}^{2} / \bar{Y}^{2}\right)$
Let $\bar{x}_{1}=\frac{1}{n_{1}} \sum_{i=1}^{n_{1}} x_{i}$ and $\bar{x}_{2}=\frac{1}{n_{2}} \sum_{i=1}^{n_{2}} x_{i}$ denote the means of the auxiliary variable of $n_{1}$ responding units and the $n_{2}$ non-responding units. Further, let $\bar{x}_{2 r}=\frac{1}{r} \sum_{i=1}^{r} x_{i}$ denote the mean of the $r=n_{2} / k$ sub sampled units. Thus, an unbiased estimator, due to Hansen and Hurwitz (1946) of the population mean $\bar{Y}$ of the study variable $y$ is given by.

$$
\begin{equation*}
\bar{x}^{*}=w_{1} \bar{x}_{1}+w_{2} \bar{x}_{2 r} \tag{3}
\end{equation*}
$$

where $w_{1}=\left(n / n_{1}\right), w_{2}=\left(n / n_{2}\right)$ are responding and non-responding proportions in the sample. The variance of ${ }^{-*}$ to terms of order $n^{-1}$ is given by,

$$
\begin{equation*}
V\left(\bar{x}^{*}\right)=\bar{X}^{2}\left\{\theta C_{x}^{2}+\lambda C_{x(2)}^{2}\right\} \tag{4}
\end{equation*}
$$

where $C_{x}^{2}=\left(S_{x}^{2} / \bar{X}^{2}\right), C_{x(2)}^{2}=\left(S_{x(2)}^{2} / \bar{X}^{2}\right)$,

$$
S_{x}^{2}=\frac{1}{N-1} \sum_{i=1}^{N}\left(x_{i}-\bar{X}\right)^{2} \text { and } S_{x(2)}^{2}=\frac{1}{N_{2}-1} \sum_{i=1}^{N_{2}}\left(x_{i}-\bar{X}_{2}\right)^{2}
$$

The expectation includes,
$\bar{y}=\bar{Y}\left(1+e_{y}\right) \bar{x}=\bar{X}\left(1+e_{x}\right) \bar{z}=\bar{Z}\left(1+e_{z}\right)$
$E\left(\bar{e}_{0}\right)=E\left(\bar{e}_{1}\right)=0$
$E\left(\bar{e}_{0}^{2}\right)=V(\bar{y} *)=\bar{Y}^{2}\left\{\theta C_{y}^{2}+\lambda C_{y(2)}^{2}\right\}$
$E\left(\bar{e}_{1}^{2}\right)=V(\bar{x} *)=\bar{X}^{2}\left\{\theta C_{x}^{2}+\lambda C_{x(2)}^{2}\right\}$
$E\left(\bar{e}_{1} \bar{e}_{0}\right)=V(\bar{y} *, \bar{x} *)=\bar{Y} \bar{X}\left\{\theta \rho_{y x} C_{x} C_{y}+\lambda \rho_{y x(2)} C_{x(2)} C_{y(2)}\right\}$
Where $\rho_{y x}=S_{y x} / S_{y} S_{x}, \quad \rho_{y x(2)}=S_{y x(2)} / S_{y(2)} S_{x(2)}$
$\rho_{2}=\frac{S_{2 x y}}{S_{2 y} S_{2 x}} \quad k_{y x}=\rho_{y x} \frac{C_{y}}{C_{x}} \quad k_{y x 2}=\rho_{y x 2} \frac{C_{y 2}}{C_{x 2}}$
$S_{y x}=\frac{1}{N-1} \sum_{i=1}^{N}\left(y_{i}-\bar{Y}\right)\left(x_{i}-\bar{X}\right) S_{y x(2)}=\frac{1}{N_{2}-1} \sum_{i=1}^{N_{2}}\left(y_{i}-\bar{Y}_{2}\right)\left(x_{i}-\bar{X}_{2}\right)$
$S_{2 y x}=\frac{1}{N-1} \sum_{i=1}^{N}\left(y_{i}-\overline{Y_{2}}\right)\left(x_{i}-\overline{X_{2}}\right) S_{2 x}=\frac{1}{N-1} \sum_{i=1}^{N}\left(x_{i}-\overline{X_{2}}\right)^{2}$
$S_{2 y}=\frac{1}{N-1} \sum_{i=1}^{N}\left(y_{i}-\overline{Y_{2}}\right)^{2} \quad \theta=\frac{N-n}{N n}$,
$\theta^{\prime}=\frac{n^{\prime}-n}{n^{\prime} n}, \quad \lambda=\frac{N-n^{\prime}}{N n^{\prime}}$ and $\delta=\frac{W_{2}(k-1)}{n}$
$A^{-1}=\frac{1}{|A|}\left(C^{T}\right)_{i j}=\frac{\operatorname{Adj}(A)}{|A|}$

$$
\begin{equation*}
\frac{|R|_{\underline{y x_{q}}}}{|R|_{\underline{x}_{q}}}=\left(1-\rho_{y: x_{q}}^{2}\right) \tag{5}
\end{equation*}
$$

Arora and Lal (1989)

The following notations will be used in deriving the mean square errors of proposed estimator
$|R|_{y x_{p}}$ Determinant of population correlation matrix of variables $y, \mathrm{x}_{1}, \mathrm{x}_{2}$
$|R|_{x_{p}}$ Determinant of population correlation matrix of variables $\mathrm{x}_{1}, \mathrm{x}_{2}$
3.1 CASE 1: When there is incomplete information on the study variable $y$ and complete information on the auxiliary variable $\boldsymbol{x}$.
When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase ratio estimator by Khare and Srivastava $(1993,1995)$ is given by,

$$
\begin{equation*}
t_{R 1}=\bar{y}^{*} \frac{\bar{x}}{\bar{x}} \tag{6}
\end{equation*}
$$

The MSE of the estimator $t_{R 1}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{R 1}\right)=\bar{Y}^{2}\left[\theta C_{y}^{2}+(\theta-\lambda) C_{y}^{2}\left(1-2 k_{y x}\right) C_{x}^{2}+\delta C_{y(2)}^{2}\right] \tag{7}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase product estimator by Khare and Srivastava $(1993,1995)$ is given by,

$$
\begin{equation*}
t_{P 1}=\bar{y}^{*} \frac{\bar{x}}{\overline{x^{\prime}}} \tag{8}
\end{equation*}
$$

The MSE of the estimator $t_{P 1}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{P 1}\right)=\bar{Y}^{2}\left[\theta C_{y}^{2}+(\theta-\lambda) C_{y}^{2}\left(1+2 k_{y x}\right) C_{x}^{2}+\delta C_{y(2)}^{2}\right] \tag{9}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase regression estimator by Khare and Srivastava $(1993,1995)$ is given by,

$$
\begin{equation*}
t_{R E 1}=\bar{y}^{*}+\beta\left(\bar{x}^{\prime}-\bar{x}\right) \tag{10}
\end{equation*}
$$

The MSE of the estimator $t_{R E 1}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{R E 1}\right)=\bar{Y}^{2}\left(\theta C_{y}^{2}+(\theta-\lambda)\left(1-\rho_{y x}^{2}\right)+\delta C_{y(2)}^{2}\right) \tag{11}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase exponential ratio estimator by Singh et al. (2010) is given by,

$$
\begin{equation*}
t_{E R 1}=\bar{y}^{*} \exp \left(\frac{\bar{x}^{\prime}-\bar{x}}{\bar{x}^{\prime}+\bar{x}}\right) \tag{12}
\end{equation*}
$$

The MSE of the estimator $t_{E R 1}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{E R 1}\right)=\bar{Y}^{2}\left[\theta C_{y}^{2}+(\theta-\lambda)\left\{C_{y}^{2}+\frac{1}{2}\left(1-2 k_{y x}\right) C_{x}^{2}\right\}+\delta C_{y(2)}^{2}\right] \tag{13}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase exponential product estimator by Singh et al. (2010) is given by,

$$
\begin{equation*}
t_{E P 1}=\bar{y}^{*} \exp \left(\frac{\bar{x}-\bar{x}^{\prime}}{\bar{x}+\bar{x}^{\prime}}\right) \tag{14}
\end{equation*}
$$

The MSE of the estimator $t_{E P 1}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{E P 1}\right)=\bar{Y}^{2}\left[\theta C_{y}^{2}+(\theta-\lambda)\left\{C_{y}^{2}+\frac{1}{2}\left(1+2 k_{y x}\right) C_{x}^{2}\right\}+\delta C_{y(2)}^{2}\right] \tag{15}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is known, the two phase exponential ratio-product estimator by Kumar and Bhougal (2011)is given by,

$$
\begin{equation*}
t_{E R P 1}=\bar{y}^{*} \exp \left(\alpha\left(\frac{\bar{x}^{\prime}-\bar{x}}{\bar{x}^{\prime}+\bar{x}}\right)+(1-\alpha)\left(\frac{\bar{x}-\bar{x}^{\prime}}{\bar{x}+\bar{x}^{\prime}}\right)\right) \tag{16}
\end{equation*}
$$

The MSE of the estimator $t_{E R P 1}$;
$\operatorname{MSE}\left(t_{E R P 1}\right)=\bar{Y}^{2}\left[\theta\left\{C_{y}^{2}+\frac{B_{2}}{A_{2}}\left(\frac{B_{2}}{A_{2}}-2 k_{y x}\right) C_{x}^{2}\right\}+\delta C_{y(2)}^{2}\right]$
(17)

Where
$A_{2}=\theta C_{x}^{2}, B_{2}=\theta k_{y x} C_{x}^{2}$ and $\quad \alpha=\frac{A_{2}+2 B_{2}}{2 A_{2}}$
3.1.1 Proposed Modified Regression Type Estimator in Two Phase Sampling in the Presence of Non-Response in the Study Variable Only.

The modified regression estimator proposed by Tum et al. (2014) is given by,

$$
\begin{equation*}
t_{E R P}=(\bar{y}+\beta(\bar{X}-\bar{x}))\left(\alpha \exp \left(\frac{\bar{Z}-\bar{z}}{\bar{Z}+\bar{z}}\right)+(1-\alpha) \exp \left(\frac{\bar{z}-\bar{Z}}{\bar{Z}+\bar{z}}\right)\right) \tag{18}
\end{equation*}
$$

We will consider the above estimator in presence of non-response in the study variable only and in both the study variable and auxiliary variables. When there is incomplete information on the study variable $y$ and complete information on the auxiliary variable $x$, our proposed Modified regression type estimator in the presence of nonresponse will be given by,

$$
\begin{equation*}
t_{7}=\left(\bar{y}_{2}^{*}+\beta\left(\bar{X}-\bar{x}_{2}\right)\right)\left(\alpha \exp \left(\frac{\bar{Z}-\bar{z}_{2}}{\bar{Z}+\bar{z}_{2}}\right)+(1-\alpha) \exp \left(\frac{\overline{z_{2}}-\bar{Z}}{\bar{Z}+\bar{z}_{2}}\right)\right) \tag{19}
\end{equation*}
$$

Substituting (5) equation in (19) we get,

$$
\begin{equation*}
t_{7}=\left(\bar{Y}\left(1+\bar{e}_{y_{2}}^{*}\right)-\beta \bar{e}_{x_{2}}\right)\binom{\alpha \exp \left(\frac{\bar{Z}-\bar{Z}\left(1+\bar{e}_{z_{2}}\right)}{\bar{Z}+\bar{Z}\left(1+\bar{e}_{z_{2}}\right)}\right)}{+(1-\alpha) \exp \left(\frac{\bar{Z}\left(1+\bar{e}_{z_{2}}\right)-\bar{Z}}{\bar{Z}+\bar{Z}\left(1+\bar{e}_{z_{2}}\right)}\right)} \tag{20}
\end{equation*}
$$

Simplifying (20), we get

$$
\begin{equation*}
t_{7}=\left(\bar{e}_{y_{2}}^{*}+\bar{Y}-\beta \bar{e}_{x_{2}}\right)\binom{\alpha \exp \left(-\frac{\bar{e}_{z_{2}}}{2}\left(1+\frac{\bar{e}_{z_{2}}}{2}\right)^{-1}\right)}{+(1-\alpha) \exp \left(\frac{\bar{e}_{z_{2}}}{2}\left(1+\frac{\bar{e}_{z_{2}}}{2}\right)^{-1}\right)} \tag{21}
\end{equation*}
$$

Expanding and ignoring the second and higher terms for each expansion of product and after simplification we can write

$$
\begin{equation*}
t_{7}=\bar{Y}+\bar{e}_{y_{2}}^{* *}-\beta \bar{e}_{x_{2}}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \bar{e}_{z_{2}} \tag{22}
\end{equation*}
$$

The mean squared error of $t_{7}$ is given by,

$$
\begin{equation*}
\operatorname{MSE}\left(t_{7}\right)=E\left(t_{7}-\bar{Y}\right)^{2}=E\left(\bar{e}_{y_{2}}^{*}-\beta \bar{e}_{x_{2}}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \bar{e}_{z_{2}}\right)^{2} \tag{23}
\end{equation*}
$$

Squaring the right sides of (23) and taking expectation and using (5), we get,

$$
\begin{align*}
& \operatorname{MSE}\left(t_{7}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2}+\beta^{2} \theta \bar{X}^{2} C_{x}^{2} \\
& \quad+\bar{Y}^{2}\left(\frac{1}{2}-\alpha\right)^{2} \theta \bar{Z}^{2} C_{z}^{2}+2 \bar{Y}\left(\frac{1}{2}-\alpha\right) \theta \bar{X} \bar{Y} C_{y} C_{z} \rho_{y z}  \tag{24}\\
& \quad-2 \beta \theta \bar{X} \bar{Y} C_{y} C_{x} \rho_{y x}-2 \bar{Y}\left(\frac{1}{2}-\alpha\right) \beta \theta \bar{X} \bar{Z} C_{x} C_{z} \rho_{x z}
\end{align*}
$$

Expanding (24) by opening brackets we get,

$$
\begin{align*}
& \operatorname{MSE}\left(t_{7}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2}+\beta^{2} \theta \bar{X}^{2} C_{x}^{2}+\frac{1}{4} \bar{Y}^{2} \theta \bar{Z}^{2} C_{z}^{2} \\
& \quad-\alpha \bar{Y}^{2} \theta \bar{Z}^{2} C_{z}^{2}+\bar{Y}^{2} \alpha^{2} \theta \bar{Z}^{2} C_{z}^{2}+\bar{Y}^{2} \theta \bar{X} C_{y} C_{z} \rho_{y z}  \tag{25}\\
& \quad-\alpha \overline{\bar{Y}^{2}} \theta \bar{Z} C_{y} C_{z} \rho_{y z}-2 \beta \theta \bar{X} \bar{Y} C_{y} C_{x} \rho_{y x}-\bar{Y} \beta \theta \bar{X} \bar{Z} C_{x} C_{z} \rho_{x z} \\
& +\alpha 2 \bar{Y} \beta \bar{X} \bar{Z} C_{x} C_{z} \rho_{x z}
\end{align*}
$$

Differentiating (25) with respect to $\alpha$ and $\beta$ and equating to zero gives

$$
\begin{array}{r}
\beta=\frac{\bar{Y} C_{y}}{\bar{X} C_{x}\left|R_{2 \times 2}\right|}(-1)^{1+1}\left|R_{y x}\right|_{y x z} \\
\alpha=\frac{1}{2}+\frac{C_{y}}{\bar{Z} C_{z}\left|R_{2 \times 2}\right|}(-1)^{2+1}\left|R_{y z}\right|_{y x z} \tag{26}
\end{array}
$$

Using normal equations that are used to find the optimum values of $\alpha$ and $\beta$ (26) can be written in simplified form as

$$
\begin{equation*}
\operatorname{MSE}\left(t_{7}\right)=E\left(\bar{e}_{y}^{*}\left(\bar{e}_{y}^{*}-\beta \bar{e}_{x}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \bar{e}_{z}\right)\right) \tag{27}
\end{equation*}
$$

Simplifying and taking expectation, we get,

$$
\begin{align*}
& \operatorname{MSE}\left(t_{7}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2}  \tag{28}\\
& \quad-\beta \theta \bar{X} \bar{Y} C_{y} C_{x} \rho_{y x}+\bar{Y} \alpha \theta \bar{Y} \bar{Z} C_{y} C_{z} \rho_{y z}
\end{align*}
$$

Substituting the optimum value in (26), we get,

$$
\begin{align*}
& \operatorname{MSE}\left(t_{t}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2} \\
& \quad-\left(\left.\frac{\bar{Y} C_{y}}{\bar{X} C_{x}\left|R_{2 x 2}\right|}(-1)^{1+1}\left|R_{y x}\right|\right|_{y z}\right) \theta \bar{X} \bar{Y} C_{y} C_{x} \rho_{y x}  \tag{29}\\
& \quad+\bar{Y}\left(\frac{1}{2}-\left(\frac{1}{2}+\frac{C_{y}}{\bar{Z} C_{z}\left|R_{2 x 2}\right|}(-1)^{2+1}\left|R_{y z}\right|_{y x z}\right)\right) \theta \bar{Y} \bar{Z} C_{y} C_{z} \rho_{y z}
\end{align*}
$$

Simplifying (29) we get

$$
\begin{equation*}
\operatorname{MSE}\left(t_{7}\right)=\theta \overline{\mathrm{Y}}^{2} C_{y}^{2}\left(1-\frac{(-1)^{1+1}\left|R_{x x}\right|_{\mid x z}}{\left|R_{2 x 2}\right|} \rho_{y x}-\frac{(-1)^{2+1}\left|R_{x x}\right|_{y x z}}{\left|R_{2 x}\right|} \rho_{x z}\right)+\lambda \bar{\gamma}^{2} C_{y(2)}^{2} \tag{30}
\end{equation*}
$$

We can rewrite (30) as,

We can also rewrite (31) as,

$$
\begin{equation*}
\operatorname{MSE}\left(t_{7}\right)=\frac{\theta \bar{Y}^{2} C_{y}^{2}}{\left|R_{2 \times 2}\right|}|R|_{y x z}+\lambda \bar{Y}^{2} C_{y(2)}^{2} \tag{32}
\end{equation*}
$$

Using Arora and Lal (1989) in (32) we get.

$$
\begin{equation*}
\operatorname{MSE}\left(t_{7}\right)=\theta \bar{Y}^{2} C_{y}^{2}\left(1-\rho_{y, x z}^{2}\right)+\lambda \bar{Y}^{2} C_{y(2)}^{2} \tag{33}
\end{equation*}
$$

3.2 CASE 2: When there is incomplete
information on both the study variable $y$ and
the auxiliary variable $x$.

Khare and Srivastava (1993, 1995) proposed ratio and product estimators under case 2 . When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase ratio estimator is given by,

$$
\begin{equation*}
t_{R 2}=\bar{y}^{*} \frac{\bar{x}^{\prime}}{\bar{x}} \tag{34}
\end{equation*}
$$

The MSE of the estimator $t_{R 2}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{R 2}\right)=\bar{Y}^{2}\binom{\theta^{\prime}\left\{C_{y}^{2}+\left(1-2 k_{y x}\right) C_{x}^{2}\right\}+}{\delta\left\{C_{y(2)}^{2}+\left(1-2 k_{y x(2)}\right) C_{x_{2}}^{2}\right\}+\lambda^{\prime} C_{y}^{2}} \tag{35}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase product estimator is given by,

$$
\begin{equation*}
t_{P 2}=\bar{y}^{*} \frac{\bar{x}^{*}}{\bar{x}^{\prime}} \tag{36}
\end{equation*}
$$

The MSE of the estimator $t_{P 2}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{P_{2}}\right)=\bar{Y}^{2}\binom{\theta^{\prime}\left\{C_{y}^{2}+\left(1+2 k_{y x}\right) C_{x}^{2}\right\}}{+\delta\left\{C_{y(2)}^{2}+\left(1+2 k_{y x(2)}\right) C_{x_{2}}^{2}\right\}+\lambda^{\prime} C_{y}^{2}} \tag{37}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase regression estimator by Khare and Srivastava $(1993,1995)$ is given by,

$$
\begin{equation*}
t_{R E 2}=\bar{y}^{*}+\beta\left(\bar{x}^{\prime}-\bar{x}^{*}\right) \tag{38}
\end{equation*}
$$

The MSE of the estimator $t_{\text {RE2 }}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{R E 2}\right)=\bar{Y}^{2}\binom{\theta^{\prime} C_{y}^{2}+\lambda\left(1-\rho^{2}\right) C_{y}^{2}}{+\delta\left(C_{y(2)}^{2}+k_{y x}\left(k_{y x}-2 k_{y x(2)}\right) C_{x(2)}^{2}\right)} \tag{39}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase exponential ratio estimator by Singh et al. (2010) is given by,

$$
\begin{equation*}
t_{E R 2}=\bar{y}^{*} \exp \left(\frac{\bar{x}^{\prime}-\bar{x}^{*}}{\bar{x}^{\prime}+\bar{x}^{*}}\right) \tag{40}
\end{equation*}
$$

The MSE of the estimator $t_{E R 2}$;

$$
\begin{equation*}
\operatorname{MSE}\left(t_{E R 2}\right)=\bar{Y}^{2}\binom{\theta^{\prime}\left\{C_{y}^{2}+\left(1-4 k_{y x}\right) \frac{C_{x}^{2}}{4}\right\}}{+\delta\left\{C_{y(2)}^{2}+\left(1-4 k_{y x(2)}\right) \frac{C_{x_{2}}^{2}}{4}\right\}+\lambda^{\prime} C_{y}^{2}} \tag{41}
\end{equation*}
$$

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase exponential
product estimator by Singh et al. (2010) is given by,

$$
\begin{equation*}
t_{E P 2}=\bar{y}^{*} \exp \left(\frac{\bar{x}^{*}-\bar{x}^{\prime}}{\bar{x}^{*}+\bar{x}^{\prime}}\right) \tag{42}
\end{equation*}
$$

The MSE of the estimator $t_{E P 2}$;

$$
\operatorname{MSE}\left(t_{E P 2}\right)=\bar{Y}^{2}\binom{\theta^{\prime}\left\{C_{y}^{2}+\left(1+4 k_{y x}\right) \frac{C_{x}^{2}}{4}\right\}}{+\delta\left\{C_{y(2)}^{2}+\left(1+4 k_{y x(2)}\right) \frac{C_{x_{z}}^{2}}{4}\right\}+\lambda^{\prime} C_{y}^{2}}
$$

(43)

When the population mean $\bar{X}$ of the auxiliary variable ' $x$ ' is unknown, the two phase exponential ratio-product estimator by Kumar and Bhougal (2011) is given by,

$$
\begin{equation*}
t_{E R P 2}=\bar{y}^{*} \exp \left(\alpha\left(\frac{\bar{x}^{\prime}-\bar{x}^{*}}{\overline{x^{\prime}+x^{*}}}\right)+(1-\alpha)\left(\frac{-\bar{x}^{*}-\bar{x}^{\prime}}{-\vec{x}^{*}+\bar{x}^{\prime}}\right)\right) \tag{44}
\end{equation*}
$$

The MSE of the estimator $t_{E R P 2}$;
$\operatorname{MSE}\left(t_{E R P 2}\right)=\bar{Y}^{2}\binom{\theta^{\prime}\left\{C_{y}^{2}+\frac{B_{2}}{A_{2}}\left(\frac{B_{2}}{A_{2}}-2 k_{y x}\right) C_{x}^{2}\right\}}{+\delta\left\{C_{y(2)}^{2}+\frac{B_{2}}{A_{2}}\left(\frac{B_{2}}{A_{2}}-2 k_{y x}\right) C_{x}^{2}\right\}+\lambda^{\prime} C_{y}^{2}}$

Where

$$
\begin{equation*}
A_{2}=\theta C_{x}^{2}+\delta C_{x(2)}^{2}, \tag{45}
\end{equation*}
$$

$$
B_{2}=\theta k_{y x} C_{x}^{2}+\delta k_{y x_{2}} C_{x(2)}^{2} \quad \alpha=\frac{A_{2}+2 B_{2}}{2 A_{2}}
$$

### 3.2.1 Modified Regression Estimator with Non-

 Response in both study variable and the auxiliary variableFollowing Tum et al. (2014), we define the following estimator for $\bar{Y}$ in the presence of nonresponse in the study variable and auxiliary variables as:

$$
\begin{equation*}
t_{8}=\left(\frac{-*}{y}+\beta\left(\bar{X}-x^{*}\right)\right)\left(\alpha \exp \left(\frac{\bar{Z}-z^{*}}{\bar{Z}+z^{*}}\right)+(1-\alpha) \exp \left(\frac{-\vec{z}-\bar{Z}}{\bar{Z}+\bar{z}^{*}}\right)\right) \tag{46}
\end{equation*}
$$

Substituting (5) equation in (46) we get,

$$
\begin{equation*}
t_{8}=\left(\bar{Y}\left(1+e_{y}^{*}\right)-\beta \bar{e}_{x}^{*}\right)\binom{\alpha \exp \left(\frac{\bar{Z}-\bar{Z}\left(1+\bar{e}_{z}^{*}\right)}{\bar{Z}+\bar{Z}\left(1+\bar{e}_{z}^{*}\right)}\right)}{+(1-\alpha) \exp \left(\frac{\bar{Z}\left(1+\bar{e}_{z}^{*}\right)-\bar{Z}}{\bar{Z}+\bar{Z}\left(1+\bar{e}_{z}^{*}\right)}\right)} \tag{47}
\end{equation*}
$$

Opening brackets and ignoring the second and higher terms for each expansion of product and after simplification we can write $t_{8}$ as

$$
\begin{equation*}
t_{8}=\bar{Y}+\bar{e}_{y}^{*}-\bar{e}_{x}^{*}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \bar{e}_{z}^{*} \tag{48}
\end{equation*}
$$

The mean squared error of $t_{8}$ is given by,

$$
\begin{equation*}
\operatorname{MSE}\left(t_{8}\right)=E\left(t_{8}-\bar{Y}\right)^{2}=E\left(-\bar{e}_{y}^{*}-\beta-\bar{e}_{x}^{*}+\bar{Y}\left(\frac{1}{2}-\alpha\right)-\bar{e}_{z}^{*}\right)^{2} \tag{49}
\end{equation*}
$$

Squaring the right sides of (49), we get,

Taking expectation and using (5) in (50), we get,

$$
\begin{align*}
& \operatorname{MSE}\left(t_{8}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2}+\theta \bar{X}^{2} \beta^{2} C_{x}^{2}+\lambda \bar{X}^{2} \beta^{2} C_{x(2)}^{2} \\
& \quad+\bar{Y}^{2}\left(\frac{1}{2}-\alpha\right)^{2}\left(\theta \bar{Z}^{2} C_{z}^{2}+\lambda \bar{Z}^{2} C_{z(2)}^{2}\right)  \tag{51}\\
& \quad+2 \bar{Y}\left(\frac{1}{2}-\alpha\right)\left(\bar{Y} \bar{X}\left(\theta \rho_{y z} C_{z} C_{y}+\lambda \rho_{y(2)} C_{z(2)} C_{y(2)}\right)\right) \\
& \quad-2 \beta \bar{X} \bar{Y}\left(\theta \rho_{y x} C_{x} C_{y}+\lambda \rho_{y x(2)} C_{x(2)} C_{y(2)}\right) \\
& \quad-2 \bar{Y} \beta\left(\frac{1}{2}-\alpha\right)\left(\bar{Y} \bar{X}\left(\theta \rho_{x z} C_{z} C_{x}+\lambda \rho_{x(2)} C_{x(2)} C_{z(2)}\right)\right)
\end{align*}
$$

Expanding and differentiating (51) with respect to $\alpha, \alpha^{*}, \beta$ and $\beta^{*}$ and equating to zero gives

$$
\begin{align*}
& \beta=\frac{\bar{Y} C_{y}}{\bar{X} C_{x}\left|R_{2 \times 2}\right|}(-1)^{1+1}\left|R_{y x}\right|_{y x z} \\
& \beta^{*}=\frac{\bar{Y} C_{y(2)}}{\bar{X} C_{x(2)}\left|R_{2 \times 2}^{*}\right|}(-1)^{1+1}(-1)^{1+1}\left|R_{y x}^{*}\right|_{y x z} \\
& \alpha=\frac{1}{2}+\frac{C_{y}}{\bar{Z} C_{z}\left|R_{2 \times 2}\right|}(-1)^{2+1}\left|R_{y z}\right|_{y x z} \\
& \alpha^{*}=\frac{1}{2}+\frac{C_{y(2)}}{\bar{Z} C_{z(2) z}\left|R_{2 \times 2}^{*}\right|}(-1)^{2+1}\left|R_{y z}{ }^{*}\right|_{y x z} \tag{52}
\end{align*}
$$

Using normal equations that are used to find the optimum values of $\alpha$ and $\beta$, (52) can be written in simplified form as,

$$
\begin{equation*}
\operatorname{MSE}\left(t_{8}\right)=E\left(\bar{e}_{y}^{*}\left(\bar{e}_{y}^{*}-\beta \bar{e}_{x}^{*}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \bar{e}_{z}^{*}\right)\right) \tag{53}
\end{equation*}
$$

Expanding and Taking expectation and using (5) in (53) we get

$$
\begin{align*}
& \operatorname{MSE}\left(t_{8}\right)=\theta \bar{Y}^{2} C_{y}^{2}+\lambda \bar{Y}^{2} C_{y(2)}^{2}-\beta \bar{X} \bar{Y} \theta \rho_{y x} C_{x} C_{y} \\
& \quad-\lambda \beta^{*} \bar{X} \bar{Y} \rho_{y x(2)} C_{x(2)} C_{y(2)}+\bar{Y}\left(\frac{1}{2}-\alpha\right) \theta \bar{Y} \bar{X} \rho_{y z} C_{z} C_{y}  \tag{54}\\
& \quad+\bar{Y}\left(\frac{1}{2}-\alpha^{*}\right) \lambda \bar{Y} \bar{X} \rho_{y z(2)} C_{z(2)} C_{y(2)}
\end{align*}
$$

Substituting the optimum value in (52), we get

$$
\begin{align*}
& \operatorname{MSE}\left(t_{8}\right)=\theta \bar{Y}^{2} C_{y}^{2}-\left(\frac{\bar{Y} C_{y}}{\bar{X} C_{x}\left|R_{2 x 2}\right|}(-1)^{\mid+1}\left|R_{y x}\right|_{y x z}\right) \theta \bar{X} \bar{Y} C_{y} C_{x} \rho_{y x} \\
& \quad+\bar{Y}\left(\frac{1}{2}-\left(\frac{1}{2}+\frac{C_{y}}{\bar{Z} C_{z}\left|R_{2 x 2}\right|}(-1)^{2+1}\left|R_{y x}\right|_{y x z}\right)\right) \theta \bar{Y} \bar{Z} C_{y} C_{z} \rho_{y z}  \tag{55}\\
& \quad+\lambda \bar{Y}^{2} C_{y(2)}^{2}-\left(\frac{\bar{Y} C_{y(2)}}{\bar{X} C_{x(2)}\left|R_{2 x z}^{*}\right|}(-1)^{1+1}(-1)^{1+1}\left|R_{y x}^{*}\right|_{y x z}\right) \lambda \bar{X} \bar{Y} C_{y(2)} C_{x(2)} \rho_{y x(2)} \\
& \quad+\bar{Y}\left(\frac{1}{2}-\left(\frac{1}{2}+\frac{C_{y(2)}}{\bar{Z} C_{z(2)]}\left|R_{2 x 2}^{*}\right|}(-1)^{2+1}\left|R_{y x}^{*}\right|_{y x z}\right)\right) \lambda \bar{Y} \bar{Z} C_{y(2)} C_{z(2)} \rho_{y(2)}
\end{align*}
$$

Simplifying (55) we get

$$
\begin{align*}
& \operatorname{MSE}\left(t_{8}\right)=\theta \bar{Y}^{2} C_{y}^{2}\left(1-\frac{(-1)^{1+1}\left|R_{y x}\right|_{y x z}}{\left|R_{2 x 2}\right|} \rho_{y x}-\frac{(-1)^{2+1}\left|R_{y z}\right|_{y z z}}{\left|R_{2 x z}\right|} \rho_{y z}\right)  \tag{56}\\
& \quad+\lambda \bar{Y}^{2} C_{y(2)}^{2}\left(1-\frac{(-1)^{1+1}\left|R_{y x}\right|_{y x z}}{\left|R_{2 x x}\right|^{*} \mid} \rho_{y x(2)}-\frac{(-1)^{2+1}\left|R_{y y}^{*}\right|_{y z z}}{\left|R_{2 x x}^{*}\right|} \rho_{y x(2)}\right)
\end{align*}
$$

Or

$$
\begin{equation*}
\operatorname{MSE}\left(t_{8}\right)=\frac{\theta \bar{Y}^{2} C_{y}^{2}}{\left|R_{2 \times 2}\right|}|R|_{y x z}+\frac{\lambda \bar{Y}^{2} C_{y(2)}^{2}}{\left|R_{2 \times 2}^{*}\right|}\left|R^{*}\right|_{y x z} \tag{57}
\end{equation*}
$$

Using Arora and Lal (1989) in (57) we get,

$$
\begin{equation*}
\operatorname{MSE}\left(t_{8}\right)=\theta \bar{Y}^{2} C_{y}^{2}\left(1-\rho_{y . x z}^{2}\right)+\lambda \bar{Y}^{2} C_{y(2)}^{2}\left(1-\rho_{y . x z}^{* 2}\right) \tag{58}
\end{equation*}
$$

## 4. Simulation, Result and Discussion

In this section, we carried out some data simulation experiments using R statistical program to compare the performance of modified regression estimators in two phase sampling with non-response in either the study variable only or both the study variable and the auxiliary variable with already existing estimators in two phase sampling for finite population. In the simulated population, the study variable and auxiliary variables are normally distributed.
i) Study variable $\mathrm{N}=500, n_{1}=75, \quad n=50 \mu=$ $75 \sigma=10$
ii) For ratio estimator the auxiliary variable is strongly positively correlated with the study variable and the line passes through the origin.
$\mathrm{N}=500, n_{1}=75, n=50 \mu=55 \sigma=9.4$
$\rho_{y x}=0.7018$
iii)For regression estimator the auxiliary variable was strongly positively correlated with the study variable and the regression line does not pass through the origin.

$$
\begin{array}{ll}
\mathrm{N}=500, & n_{1}=75 \text { and } n=50 . \mu=22 \\
\sigma=3.29 & \rho_{y x}=0.8114
\end{array}
$$

iv)For product estimator the auxiliary variable was strongly negatively correlated with the study variable.

$$
\begin{aligned}
& \mathrm{N}=500, n_{1}=75 \text { and } n=50, \mu=34 \sigma=5.10 \\
& \rho_{y x}=-0.7477
\end{aligned}
$$

The percent relative efficiencies (PREs) of different proposed estimators were computed with respect to a usual unbiased estimator $\bar{y}^{*}$ for different values of $k$.

$$
\begin{equation*}
\operatorname{PRE}(\hat{t})=\frac{\operatorname{Var}\left(\bar{y}^{*}\right)}{\operatorname{MSE}(\hat{t})} * 100 \tag{59}
\end{equation*}
$$

Table 1: Percent relative efficiency of different $\bar{Y}$ estimators with respect to $\bar{y}^{*}$ when the nonresponse is on the study variable only in two phase sampling.

| Estimators | $1 / k$ |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
|  | $1 / 5$ | $1 / 4$ | $1 / 3$ | $1 / 2$ |
|  | 100 | 100 | 100 | 100 |
| $t_{R 1}$ | 110 | 114 | 116 | 117 |
| $t_{P 1}$ | 101 | 101 | 102 | 105 |
| $t_{R E 1}$ | 129 | 140 | 143 | 157 |
| $t_{E R 1}$ | 126 | 135 | 138 | 150 |
| $t_{E P 1}$ | 106 | 107 | 110 | 111 |


| $t_{E R P 1}$ | 126 | 136 | 139 | 151 |
| :--- | :--- | :--- | :--- | :--- |
| $t_{7}$ (Proposed) | $\mathbf{1 3 9}$ | $\mathbf{1 5 5}$ | $\mathbf{1 6 1}$ | $\mathbf{1 8 3}$ |

The Percent relative efficiencies of all the estimators in the Table I increases as k increases. Our proposed estimator $\left(t_{7}\right)$ is the most efficient among all the estimators since it has the highest Percent relative efficiency when the non-response is on the study variable only in two phase sampling Table 2: Percent relative efficiency of different $\bar{Y}$ estimators with respect to $\bar{y}^{*}$ when the nonresponse is on the study variable and also in auxiliary variable in two phase sampling.

| Estimators | $1 / k$ |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
|  | $1 / 5$ | $1 / 4$ | $1 / 3$ | $1 / 2$ |
| $\bar{y}^{*}$ | 100 | 100 | 100 | 100 |
| $t_{R 2}$ | 104 | 105 | 133 | 119 |
| $t_{P 2}$ | 102 | 105 | 106 | 106 |
| $t_{\text {RE } 2}$ | 202 | 205 | 213 | 219 |
| $t_{\text {ER2 }}$ | 176 | 180 | 191 | 181 |
| $t_{\text {EP2 }}$ | 154 | 138 | 133 | 124 |
| $t_{\text {ERP2 }}$ | 197 | 174 | 182 | 180 |
| $t_{8}$ <br> (Proposed) | $\mathbf{2 6 9}$ | $\mathbf{2 6 8}$ | $\mathbf{2 7 3}$ | $\mathbf{2 6 1}$ |

Our proposed estimator $\left(t_{8}\right)$ is the most efficient among all the estimators since it has the highest Percent relative efficiency when the non-response
are on the study variable and the auxiliary variable in two phase sampling.

### 5.0 Conclusion

Based on these study results, the proposed estimators $t_{7}$ and $t_{8}$ are recommended for use in practice when non-response is on the study variable only and on both the study variable and the auxiliary variable in two phase sampling respectively.

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